# UBA2013/L3

# HB driver IC with PFC for fluorescent rings

Rev. 00.01 — 23 February 2007

**Preliminary data sheet** 

## 1. General description

The UBA2013/L3 is a high voltage IC intended to drive and control fluorescent lamps. The IC can handle both cold and warm ignition of the lamp. It contains a  $T_{ON}$ -controlled PFC function, a half bridge controller circuit with level shifter and an internal bootstrap diode to drive an external half bridge. UBA2013/L3 also offers a functionality to properly handle fault conditions such as capacitive mode switching, end-of-lamp-life and overcurrent. UBA2013/L3 is designed for wide-input mains voltage (120 V - 277 V) applications.

## 2. Features

#### 2.1 Half bridge

- Suitable for cold and warm ignition
- Adjustable preheat time
- Adjustable ignition voltage
- Integrated bootstrap function
- Protection for lamp failure and end-of-life
- Adjustable preheat current
- Single ignition attempt
- Automatic restart after relamping
- Protection for capacitive mode

## 2.2 PFC

- Three pin PFC controller using T<sub>ON</sub> control
- Critical mode operation

#### Overvoltage/overcurrent protection

## 3. Applications

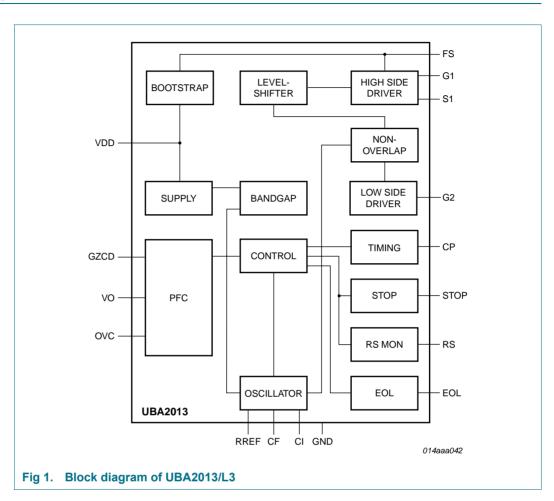
The UBA2013/L3 can provide the drive and control function for a wide range of half bridge based ballast applications at different mains voltages.

## 4. Ordering information

Table 1. Ordening mormation				
Type number	ype number Package			
	Name	Description	Version	
UBA2013T	SO16	plastic small outline package; 16 leads; body width 3.9mm	SOT109-1	

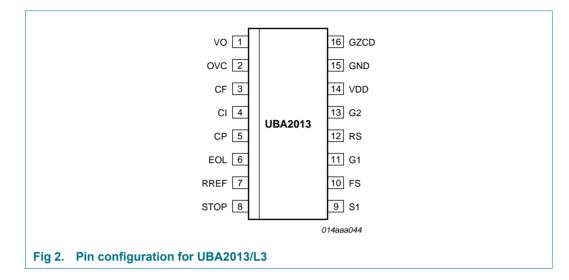
#### Table 1. Ordering information

# 5. Block diagram



# 6. Pinning information

## 6.1 Pinning



## 6.2 Pin description

#### Table 2. Pin description

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Symbol	Pin	Description
VO	1	PFC output voltage sensing
OVC	2	PFC overvoltage/current
CF	3	Oscillator capacitor
CI	4	Integrating capacitor
CP	5	Timing capacitor
EOL	6	End-of-life
RREF	7	Reference resistor
STOP	8	Stop
S1	9	Source high side transistor (T1)
FS	10	High side floating supply
G1	11	Gate high side transistor (T1)
RS	12	Current sensor
G2	13	Gate low side transistor (T2)
VDD	14	Low voltage supply
GND	15	Ground
GZCD	16	PFC gate and ZCD

## 7. Functional description

#### 7.1 Start-up state

Initial start up can be achieved by means of charging the VDD low voltage supply capacitor (C2 in the application diagram Figure 6) via an external start-up resistor. Start-up state is one of the non-oscillating sub-states. MOSFET T2 conducts and T1 is non-conducting, ensuring bootstrap capacitor C3 to be charged. In this state the circuit will be reset. The GZCD pin is pulled down and  $I_{VO(ref)}$  is not active. If  $V_{STOP} < V_{STOP(reset)}$  at the transition of  $V_{DD}$  exceeding  $V_{DD(start)}$ , the IC will enter the oscillating state. If not it will enter the stop state.

#### 7.2 Half bridge oscillator

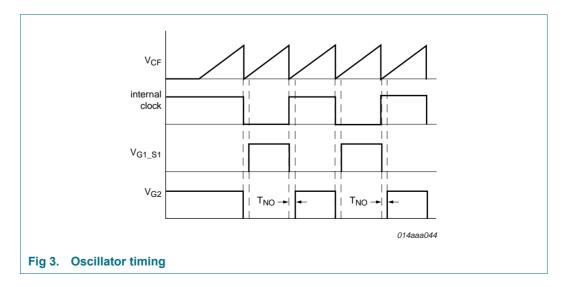
Oscillation of the half bridge is controlled by a built-in current-controlled oscillator which generates a sawtooth waveform at the CF pin. The sawtooth frequency is twice the half bridge frequency, and is determined by the capacitor at the CF pin and the current-out of pin CF, as controlled by the voltage at the CI pin. Frequency modulation is achieved by charging and discharging the CI capacitor. The IC brings MOSFETs T1 and T2 alternately into conduction with a duty factor of just below 50% each (except for situations where  $V_{RS}$  exceeds  $V_{RS(clamp)}$ ). Figure 3 represents the timing of the IC. The circuit block 'non-overlap' generates a non-overlap time  $t_{no}$  that ensures periods of exclusive conduction of T1 or T2. Time  $t_{no}$  depends on the reference current  $I_{RREF}$ .

### 7.3 Oscillating state

Oscillating state can be entered:

- when in the startup state V<sub>STOP</sub> < V<sub>STOP</sub>(reset) at the moment V<sub>DD</sub> reaches V<sub>DD(start)</sub>
- when in the VddLow state, when  $V_{STOP} < V_{STOP(ref)}$  at the moment  $V_{DD}$  reaches  $V_{DD(start)}$ .

The oscillating state has three sub-states: the preheat state, the ignition state and the burn state. The circuit always starts oscillating in the preheat state.



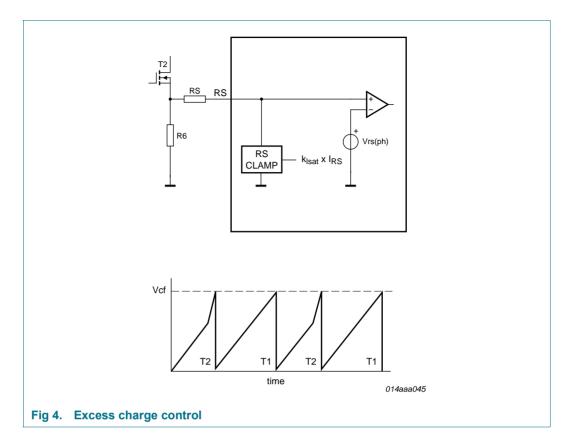
#### 7.4 Preheat state

The circuit starts oscillating at the half-bridge frequency  $f_{start}$  (approximately 2.5 x  $f_B$ ). The frequency gradually decreases until a user-defined value of the preheat current is reached. The slope of the decrease in frequency is determined by the capacitor at the CI pin. During preheat, the circuit monitors the inductor current by measuring the voltage across external resistor RS at the end of the conduction of T2 with decision level  $V_{RS(ph)}$ . The frequency is decreased for as long as  $V_{RS} < V_{RS(ph)}$ . The frequency is increased for  $V_{RS} > V_{RS(ph)}$ . During preheat the STOP pin is discharged to ground via a switch with an on resistance of  $R_{STOP(disch)}$ . The cycle-by-cycle excess charge control mechanism described in the ignition state is not active during the preheat state. The preheat time is determined by capacitor CP. For cold ignition the preheat time can be reduced by choosing a smaller CP capacitor. The circuit can be locked in the preheat state by connecting pin CP to ground.

#### 7.5 Ignition state

After the preheat time the ignition state is entered and the frequency will sweep down due to charging of the capacitor at the CI pin with the internally fixed current  $I_{Cl(charge)}$ . During this decrease in frequency, the circuit approaches the resonance frequency of the load. This will cause a high voltage across the load, which normally ignites the lamp.

In order to limit voltages and currents in the resonant circuit in case of non- or delayed ignition, a cycle-by-cycle excess charge control mechanism is used to prevent deep saturation and to limit the lamp voltage. When the voltage at pin RS exceeds  $V_{RS(clamp)}$  the impedance of the pin changes from essentially infinite to essentially zero. If a current is flowing into pin RS during the on-state of T2, a fraction  $k_{lsat}$  of that current will be fed into the capacitor  $C_{CF}$  at pin CF in addition to the oscillator current already flowing into  $C_{CF}$ . The amount of current fed into  $C_{CF}$  depends on the voltage across RS and the value of resistor R, see Figure 4. The increased current rapidly (but not instantly) ends the oscillator half-cycle, after which T2 is switched off. The on-time of T1 is not affected and thus the half bridge will run asymmetrically, see Figure 4.



#### 7.6 Burn state

At the end of the ignition time, the burn state is entered. In this state the voltage at the CI pin will continue to increase until a clamp level is reached corresponding to the minimum frequency  $f_B$ . The circuit will continue to oscillate at the minimum frequency, unless capacitive mode is detected. In the burn state the CP pin is pulled to ground with a discharge impedance  $R_{CP(disch)}$ . The EOL protection is enabled. The excess charge control mechanism will remain active.

#### 7.7 Capacitive mode protection

Capacitive mode protection is active in all oscillating states. The signal across resistor RS (R6 in the application diagram of Figure 6) also gives information about the switching behavior of the half bridge. If the voltage across resistor RS is not below  $V_{RS(cap)}$  at the moment of turn-on of T2, the capacitive mode detection circuit assumes the circuit to be in capacitive mode. Upon capacitive mode detection CI is gradually discharged and instantly the frequency gradually increases as long as capacitive mode is detected. The frequency decreases gradually down to the minimum frequency if no capacitive mode is detected. Detecting capacitive mode at the maximum frequency will activate the internal current  $I_{STOP(ch)}$  that charges the STOP pin.

#### 7.8 Stop function

For all oscillating states the IC will enter the stop state for  $V_{STOP} > V_{STOP(ref)}$ . Note that there is no internal stop timing. An external stop timing can be obtained via the RC time of the network R4, R5 and C11, see the application diagram in Figure 6. During preheat the

STOP pin is discharged to ground via a switch with on-resistance  $R_{STOP(disch)}$ . In case of a VO-low condition (see <u>Section 7.15</u>), the STOP pin is discharged with a current  $I_{STOP(dis)}$ . Apart from the preheat state or a VO-low condition, the IC will not discharge the STOP pin at any VDD.

#### 7.9 End-of-life protection

The end-of-life circuit is only active in the burn state and consists of a voltage window comparator circuit. It compares the voltage at the EOL pin with two internal reference voltages. When the voltage at the EOL pin is above  $V_{EOL(high)}$  or below  $V_{EOL(low)}$  the 'end-of-life' protection circuit activates the internal current source  $I_{STOP(ch)}$  that charges the STOP pin. The 'end-of-life' protection is not active in case of a VO-low condition (see Section 7.15).

#### 7.10 Non-oscillating state

Transitions to the non-oscillating state are always made during a G2 high condition in the half bridge (lower MOSFET T2 conducting). In the non-oscillating state T1 is off, T2 is on, the PFC control function is stopped by pulling the GZCD pin down to ground continuously, and reference current  $I_{VO(ref)}$  is switched off. Additionally, the CP and CI pins are discharged to ground. The non-oscillating state has three sub-states: the start-up state, the stop state and the VddLow state.

#### 7.11 Start-up state

Described at the beginning of this functional description.

#### 7.12 Stop state

The circuit will enter the stop state:

- when in any of the oscillating states V<sub>STOP</sub> > V<sub>STOP(ref)</sub>
- when in the VddLow state V<sub>STOP</sub> > V<sub>STOP(ref)</sub> at the moment V<sub>DD</sub> exceeds V<sub>DD(start)</sub>
- when in the startup state V<sub>STOP</sub> > V<sub>STOP(reset)</sub> at the moment V<sub>DD</sub> exceeds V<sub>DD(start)</sub>.

In the stop state, a clamp circuit is active, limiting the voltage at the VDD pin to  $V_{DD(clamp)}$ . The IC goes from the stop state into the startup state if  $V_{DD}$  drops below  $V_{DD(reset)}$ .

#### 7.13 VddLow state

The circuit will enter VddLow state in any of the oscillating states when  $V_{DD}$  drops below  $V_{DD(low)}$ . The circuit then goes from VddLow state to:

- the startup state if V<sub>DD</sub> drops below V<sub>DD(reset)</sub>
- the stop state if V<sub>STOP</sub> > V<sub>STOP(ref)</sub> at the moment V<sub>DD</sub> exceeds V<sub>DD(start)</sub>, or
- the preheat state if V<sub>STOP</sub> < V<sub>STOP(ref)</sub> at the moment V<sub>DD</sub> exceeds V<sub>DD(start)</sub>.

#### 7.14 PFC function

The internal PFC control block provides a  $T_{ON}$  controlled, critical mode power factor correction controller. The  $T_{ON}$  is set by the voltage at the VO pin. The duration of the  $T_{ON}$  pulse decreases linearly with increasing  $V_{VO}$ . The  $V_{VO}$  voltage is the result of an error current through the compensation impedance connected at the VO pin. This error current is the difference between a current proportional to the output voltage of the PFC pulling the VO pin high and an internal reference current  $I_{VO(ref)}$  pulling the VO pin low.

The external MOSFET is primarily driven via the secondary winding on the inductor L<sub>P1</sub>. The T<sub>ON</sub> timing starts the moment V<sub>GZCD</sub> exceeds V<sub>GZCD(start)</sub> (below the threshold of the external MOSFET). The external MOSFET is turned on and current builds up in the inductor L<sub>P1</sub>. At the end of T<sub>ON</sub> the output driver pulls the GZCD pin down during a defined time T<sub>OFF</sub>. This turns off the external MOSFET. The inductor current I<sub>LP1</sub> now flows through the boost diode DP2. The polarity of the voltage across the secondary winding changes to negative, keeping the external MOSFET in the off state. As long as V<sub>GZCD</sub> is below V<sub>GZCD(start)</sub> the T<sub>ON</sub> timing is reset. The current in the inductor decreases linearly to below zero. Just after the zero crossing the polarity of the voltage across the secondary winding turning on the external MOSFET and completing the cycle.

 $T_{ON}$  varies linearly from  $T_{ON(max)}$  to  $T_{ON(min)}$  in the range of  $V_{VO}$  from  $V_{VO(low)}$  to  $V_{VO(low)} + \Delta V_{VO}$ . Above a voltage  $V_{VO(off)}$  (> $V_{VO(low)} + \Delta V_{VO}$ ) at the VO pin,  $T_{ON}$  is zero and the GZCD pin is continuously pulled down.

The OVC pin is intended for over-voltage and/or over-current protection. The voltage at the OVC pin is compared to a reference voltage  $V_{OVC(ref)}$ . For  $V_{OVC} > V_{OVC(ref)}$  the GZCD pin is pulled down within a time  $T_{OVC}$ . As long as  $V_{OVC} > V_{OVC(ref)}$  the GZCD pin will be continuously pulled down by the output driver. Additionally, the OVC pin provides protection against an accidental open circuit of the external OVC divider of the PFC output voltage. As long as  $V_{OVC} < V_{OVC(low)}$  the GZCD pin is continuously pulled down by the output driver.

In order to prevent persistent ambiguous drive signals for the external MOSFET, for V<sub>GZCD</sub> > V<sub>GZCD(start)</sub> the GZCD pin is charged after a delay of T<sub>GZCD</sub> with a current of I<sub>GZCD(on)</sub> up to a voltage of V<sub>GZCD(active)</sub> (above the threshold of the external MOSFET). Note that the voltage at the GZCD pin is not clamped at V<sub>GZCD(active)</sub>: the secondary winding on the inductor L<sub>P1</sub> can take the GZCD pin up to V<sub>DD</sub>.

The PFC function is self-starting by means of a current source  $I_{GZCD(start)}$  (<<  $I_{GZCD(on)}$ ) which, under oscillation conditions, continuously charges the GZCD pin. In any of the non-oscillating states the current sources  $I_{GZCD(start)}$  and  $I_{VO(ref)}$  are off and the GZCD pin is continuously pulled down. In oscillating conditions the positive voltage at the VO pin is clamped at a level  $V_{VO(clamp)}$ : in non-oscillating conditions, the positive voltage at the VO pin is clamped at a level <  $V_{VO(off)}$ .

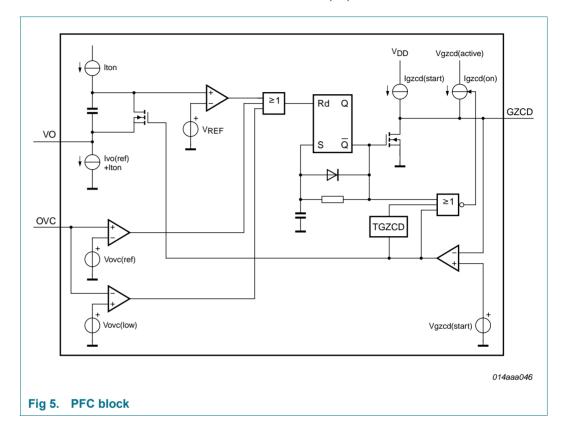
#### 7.15 VO-low condition

In order to prevent unintended stopping in case of the mains voltage being too low for the PFC stage to maintain its intended output voltage, this condition is detected in the oscillating state by the current sunk into the VO pin dropping below  $k_{VO}$ \*I<sub>VO(ref)</sub>, where the constant  $k_{VO}$  represents a fraction (typ. 95%) of I<sub>VO(ref)</sub>. In case of a VO-low condition:

the end-of-life protection is deactivated,

- the stop level is effectively raised by discharging the STOP pin with a current  $I_{\mbox{STOP}(\mbox{dis})}.$ 

The VO-low condition is overruled when V<sub>OVC</sub><V<sub>OVC(low)</sub>.



#### 7.16 State and transition diagrams

See Section 16.1.

#### 7.17 Charge coupling

Via parasitic capacitive coupling to high-voltage AC signals present in the application, a repetitive AC charge injection might occur at the IC-pins. In the typical application of Figure 6, the pins R<sub>REF</sub> and C<sub>F</sub> are most sensitive to this charge injection. For a charge coupling of Q<sub>coupl</sub>, safe functional operation of the IC is guaranteed, irrespective of the current level. Charge coupling at current levels below 50  $\mu$ A will not interfere with the accuracy of the V<sub>RS(cap)</sub> and V<sub>RS(ph)</sub> levels. Charge coupling at current levels below 20  $\mu$ A will not interfere with the accuracy of any parameter.

## 8. Limiting values

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>FS</sub>	High-side floating supply voltage	Operating t<0.5s		0	570 630	V
V <sub>RS</sub>	Voltage at pin RS		[3]	0	$V_{BE}$	V
I <sub>RS</sub>	Current in pin RS	t<1.0μs	[4]	-10	10	mA
V <sub>G1</sub>	Voltage at pin G1		[3]	$V_{S1}$ - $V_{BE}$	V <sub>FS</sub>	V
V <sub>G2</sub>	Voltage at pin G2		[3]	-V <sub>BE</sub>	V <sub>VDD</sub>	V
V <sub>VDD</sub>	Low-voltage supply	t<0.5s over lifetime		0	15	V
V <sub>VDD</sub>	Low-voltage supply	In stop state		0	14	V
I <sub>VDD</sub>	Clamp current in pin VDD				5	mA
V <sub>GZCD</sub>	Voltage at pin GZCD		[3]	-V <sub>BE</sub>	$V_{VDD}$	V
V <sub>OVC</sub>	Voltage at pin OVC			0	5	V
I <sub>VO</sub>	Current in pin VO	V <sub>VDD</sub> = 0V to V <sub>VDDmax</sub>		0	200	μA
I <sub>CF</sub>	Current in pin CF	V <sub>VDD</sub> = 0V to V <sub>VDDmax</sub>		0	200	μA
I <sub>EOL</sub>	Current in pin EOL	V <sub>VDD</sub> = 0V to V <sub>VDDmax</sub>		-1	1	mA
SR	Slew rate at pins S1, G1 and FS	With respect to ground		-4	4	V/ns
Tj	Junction temperature			-25	150	°C
T <sub>amb</sub>	Ambient temperature			-25	100	°C
T <sub>stg</sub>	Storage temperature			-55	150	°C
V <sub>esd(HBM)</sub>	HBM electrostatic handling voltage pin EOL and G1 pins FS, S1, VDD and G2 pins VO, OVC, CF, CI, CP,		<u>[1]</u>		<500 1000 2000	V V V
V <sub>esd(MM)</sub>	RREF, STOP, RS, GZCD MM electrostatic handling voltage		[2]			
	pin EOL				50	V
	pins FS, G1, S1, VDD and G2 pins VO, OVC, CF, CI, CP,				100	V
	RREF, STOP, RS, GZCD				200	V
Q <sub>coupl</sub>	Charge coupling at pins RREF and CF	Operating		-8	8	рС
R <sub>RREF</sub>	Reference resistor			22	47	kΩ

[1] In accordance with the Human Body Model (HBM): i.e. equivalent to discharging a 100 pF capacitor through a 1.5 k $\Omega$  series resistor.

[2] In accordance with the Machine Model (MM): i.e. equivalent to discharging a 200 pF capacitor through a 10  $\Omega$  series resistor and a 0.75  $\mu$ H inductor.

- [3] At  $T_{amb}$  = 25 °C the typical V<sub>BE</sub> is 0.7 V.
- [4] At negative RS currents (typ. < -5 mA) capacitive-mode protection can be triggered.

## 9. Thermal characteristics

Table 4.	Thermal characteristics			
Symbol	Parameter	Conditions	Тур	Unit
R <sub>th(j-a)</sub>	thermal resistance from junction to ambient SO16	in free air	100	K/W
$R_{th(j-pin)}$	thermal resistance from junction to pin SO16	in free air	50	K/W

## **10. Characteristics**

#### Table 5.Characteristics

 $T_{amb}$  = 25 °C;  $V_{VDD}$  = 13.0 V;  $C_{CF}$  = 100 pF;  $R_{RREF}$  = 33 k $\Omega$ ;  $C_{CP}$  = 100 nF;  $C_{Cl}$  = 100 nF; all voltages referenced to ground unless otherwise specified.

	-						
Symbol	Parameter	Conditions		Min	Тур	Мах	Unit
High-voltage	supply						
I <sub>L1</sub>	Leakage current: high-voltage pins	FS, G1, S1 = 630 V, V <sub>VDD</sub> = 0 V				15	μA
Start-up state							
V <sub>DD(start)</sub>	Start of oscillation			12.1	12.6	13.1	V
V <sub>DD(low)</sub>	Stop of oscillation			9.7	10.2	10.7	V
V <sub>DD(hys)</sub>	Start-stop hysteresis			2.2	2.4	2.6	V
I <sub>VDD(nonosc)</sub>	Non-oscillating current	VVDD = 12 V	[2]	100	150	200	μA
V <sub>DD(clamp)</sub>	Clamp voltage VDD	At 5 mA non-oscillating		10.0	12.0	14.0	V
V <sub>DD(reset)</sub>	Reset voltage		[10]	4.5	5.5	6.5	V
Preheat volta	ge						
f <sub>start</sub>	Starting frequency	V <sub>CI</sub> = 0	<u>[1]</u>	101	112.5	124	kHz
T <sub>PH</sub>	Preheat time	C <sub>CP</sub> = 100 nF		574	674	796	ms
I <sub>CP(charge)</sub>	Charge current at CP pin	V <sub>CP</sub> = 1.0 V			6.0		μA
I <sub>CP(discharge)</sub>	Discharge current at CP pin	V <sub>CP</sub> = 3.5 V			6.0		μA
$\Delta V_{CP(pk)}$	Peak voltage difference at CP pin	When timing			2.45		V
V <sub>CP(min)</sub>	CP comparator level low			1.10	1.25		V
V <sub>RS(ph)</sub>	Control voltage at RS pin		<u>[5]</u>	365	400	435	mV
Ignition state							
T <sub>IG</sub>	Ignition time	C <sub>CP</sub> = 100 nF		512	611	730	ms
V <sub>RS(clamp)</sub>	Saturation current detection level	At I <sub>RS(ig)</sub> = 0.5 mA			0.75		V
k <sub>lsat</sub>	Saturation control current gain		<u>[6]</u>	0.45	0.50	0.55	A/A
Burn state							
f <sub>B</sub>	Bottom frequency		<u>[1]</u>	43.6	45.0	46.4	kHz
T <sub>NO</sub>	Non-overlap time			1.05	1.40	1.75	μS
SYM f <sub>B</sub>	Symmetry half bridge		<u>[1][9]</u>	0.9	1.0	1.1	
SYM T <sub>NO</sub>	Symmetry non-overlap time		[11]		1.0		

#### Table 5. Characteristics ...continued

 $T_{amb}$  = 25 °C;  $V_{VDD}$  = 13.0 V;  $C_{CF}$  = 100 pF;  $R_{RREF}$  = 33 k $\Omega$ ;  $C_{CP}$  = 100 nF;  $C_{CI}$  = 100 nF; all voltages referenced to ground unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Мах	Unit
I <sub>tot</sub>	Total supply current		<u>[1][7]</u>		1.5	2.0	mA
I <sub>CI(charge)</sub>	Charge current at CI pin	V <sub>CI</sub> = 1.5 V		36	44	52	μA
I <sub>CI(discharge)</sub>	Discharge current at CI pin	V <sub>CI</sub> = 1.5 V		74	90	106	μA
$\Delta I_{CF} / \Delta V_{CI}$	CI transconductance	V <sub>CI</sub> = 1.5 V			12		μA/V
V <sub>RS(cap)</sub>	Capacitive-mode control voltage		[8]	-40	-20	0	mV
V <sub>RREF</sub>	Reference voltage			2.425	2.500	2.575	V
V <sub>G1(on)</sub>	On voltage at pin G1	I <sub>G1</sub>   = 1 mA		10.5			V
V <sub>G1(off)</sub>	Off voltage at pin G1	I <sub>G1</sub>   = 1 mA				0.3	V
VG2(on)	On voltage at pin G2	I <sub>G2</sub>   = 1 mA		10.5			V
VG2(off)	Off voltage at pin G2	I <sub>G2</sub>   = 1 mA				0.3	V
R <sub>G1(on)</sub>	High side driver on resistance	V <sub>(G1-S1)</sub> = 3 V			250		Ω
R <sub>G1(off)</sub>	High side driver off resistance	V <sub>(G1-S1)</sub> = 3 V			35		Ω
R <sub>G2(on)</sub>	Low side driver on resistance	V <sub>G2</sub> = 3 V			250		Ω
R <sub>G2(off)</sub>	Low side driver off resistance	V <sub>G2</sub> = 3 V			35		Ω
V <sub>drop</sub>	Voltage drop at bootstrap switch	I <sub>FS</sub> = 5 mA			2.0		V
R <sub>CP(disch)</sub>	On resistance switch at CP pin	V <sub>CP</sub> = 0.6 V			120		Ω
Stop and end	l-of-life						
V <sub>STOP(ref)</sub>	Stop reference level			1.21	1.26	1.31	V
V <sub>STOP(reset)</sub>	Stop reset level		[10]	0.95	1.00	1.05	V
V <sub>STOP(hys)</sub>	Stop hysteresis		[10]	0.20	0.25	0.30	V
I <sub>STOP(ch)</sub>	Stop-charge current source	V <sub>STOP</sub> = 0.75 V		2.0	2.5	3.0	μA
I <sub>STOP(dis)</sub>	Stop discharge current	V <sub>STOP</sub> = 0.75 V		0.35	0.50	0.65	μA
$R_{\text{STOP}(\text{disch})}$	On resistance discharge switch	V <sub>STOP</sub> = 0.5 V		1.0	2.5	4.0	kΩ
$V_{EOL(high)}$	High level end-of-life comparator			2.9	3.0	3.1	V
V <sub>EOL(low)</sub>	Low level end-of-life comparator			1.9	2.0	2.1	V
Power-factor	control						
I <sub>VO(ref)</sub>	Output voltage reference current	V <sub>VO</sub> = 3.0 V		97	102	107	μA
V <sub>OVC(ref)</sub>	OVC reference level			1.21	1.26	1.31	V
T <sub>OVC</sub>	Delay OVC comparator				60		ns
V <sub>VO(low)</sub>	VO offset voltage				1.0		V
$\Delta V_{VO}$	VO dynamic range				2.7		V
I <sub>GZCD(start)</sub>	Start-up current at GZCD pin	V <sub>GZCD</sub> = 0 V		35	42.5	50	μA
I <sub>GZCD(on)</sub>	Turn on current at GZCD pin	V <sub>GZCD</sub> = 3 V			12		μA
V <sub>GZCD(start)</sub>	GZCD start level			1.9	2.0	2.1	V
V <sub>GZCD(active)</sub>	GZCD active level	I <sub>GZCD</sub> = 0.5 mA			6.4		V
T <sub>GZCD</sub>	GZCD turn on delay				0.5		μS
T <sub>ON(max)</sub>	Maximum on time	$V_{VO} = V_{VO(low)}$	[4]	20			μS
T <sub>ON(min)</sub>	Minimum on time	$V_{VO} = V_{VO(off)}$	<u>[3][10]</u>		0.4	0.5	μS
I <sub>GZCD(sink)</sub>	Gate drive sink current	$V_{GZCD} = 4 V$		200			mA

#### Table 5. Characteristics ...continued

 $T_{amb}$  = 25 °C;  $V_{VDD}$  = 13.0 V;  $C_{CF}$  = 100 pF;  $R_{RREF}$  = 33 k $\Omega$ ;  $C_{CP}$  = 100 nF;  $C_{CI}$  = 100 nF; all voltages referenced to ground unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
T <sub>OFF</sub>	Duration off pulse			0.9		μS
V <sub>OVC(low)</sub>	OVC low voltage			120		mV
k <sub>VO</sub>	VO low factor		0.86	0.95	0.99	
V <sub>VO(off)</sub>	Off voltage PFC			3.7		V
V <sub>VO(clamp)</sub>	Active VO clamp voltage	I <sub>VO</sub> = 200 μA		4.7		V
V <sub>VO(pas)</sub>	Passive VO clamp voltage	$I_{VO}$ = 200 $\mu$ A, $V_{VDD}$ = 0 V		3.9		V

[1] Excluding situations where the excess charge control mechanism is active.

[2] The non-oscillation current is specified in a temperature range of 0 to 100 °C. For Tj < 0 °C and Tj > 100 °C the maximum start-up current is 350 μA.

[3] Minimum on-time is defined without the external MOSFET.  $V_{GZCD}$  is increased from 0 to 10 V in 1µs.  $T_{ONmin}$  is defined as the time elapsed between  $V_{GZCD}$  exceeding  $V_{GZCD}$ (start) and  $V_{GZCD}$  being pulled below 3 V at turn-off.

- [4] Maximum on-time is defined without the external MOSFET. Parameter is measured with  $V_{VO} = V_{VO(low)}$  and  $V_{GZCD}$  is increased from 0 to 10 V in 1µs.  $T_{ONmax}$  is defined as the time elapsed between  $V_{GZCD}$  exceeding  $V_{GZCD}(start)$  and  $V_{GZCD}$  pulled below 3 V at turn- off.
- [5] Data sampling of  $V_{RS(ph)}$  is performed at the end of conduction of T2 .
- [6] Gain is defined as  $I_{CF}/I_{RS}$  with  $V_{RS}>V_{RS(clamp)}$ .
- [7] Total supply current is specified in a T<sub>i</sub> temperature range of -20 °C to 125 °C at f<sub>B</sub>, excluding gate drive charge.
- [8] Data sampling of  $V_{RS(cap)}$  is performed at the start of conduction of T2 .
- [9] The symmetry SYM  $f_B$  is calculated from the quotient SYM  $f_B = T1_{tot}/T2_{tot}$ , with T1<sub>tot</sub> being the time between turn-off of G2 and the turn-off of G1, and T2<sub>tot</sub> the time between turn-off of G1 and the turn-off of G2.
- [10] Not measured, guaranteed by design.
- [11] The symmetry SYM  $T_{NO}$  is defined as the ratio between deadtime1 and deadtime2. Deadtime1 is the time between turning off G1 and turning on G2. Deadtime2 is the time between turning off G2 and turning on G1.

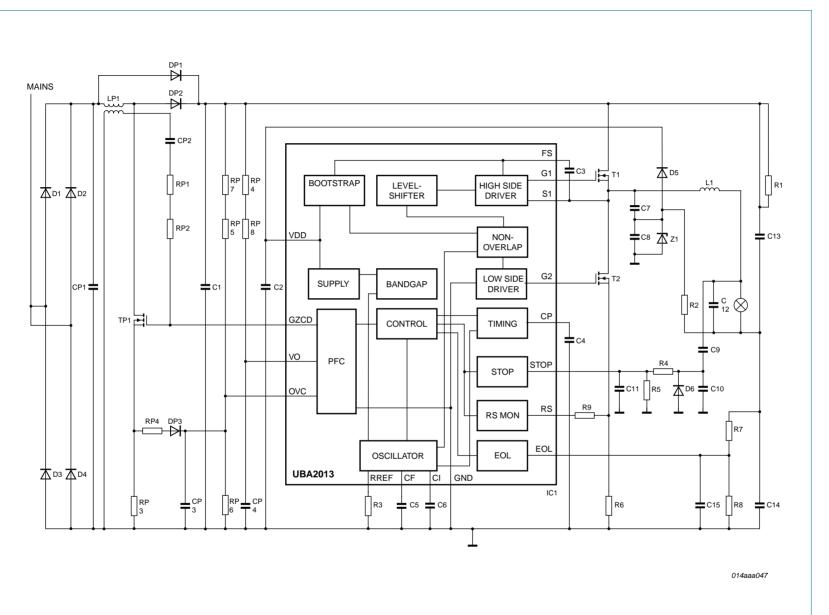
#### 11. Latch-up

#### Table 6.Latch-up

(Positive currents flow into pins)

Symbol	Parameter	Conditions	Min	Unit
I <sub>latch up</sub>	Latch-up current	<u>[1]</u>		
	Pin RS	<u>[1]</u>	-30	mA
	Pin CF	<u>[1]</u>	-50	mA
	Pin STOP	<u>[1]</u>	-80	mA
	Pins VO, OVC, CI, CP, EOL, RREF, STOP, S1, FS, G1, G2, GZCD	<u>[1]</u>	-100	mA

 Negative latch-up currents tested at T<sub>j</sub> = 150 °C by discharging a 22 mF capacitor through a 50 Ω series resistor. Positive latch-up currents according to quality specification.



# 12. Application information

## 12.1 Design equations

Equation 1 through Equation 5 give the design equations for the UBA2013:

Table 7.         UBA2013 parameters (typical)	
X1 = 3.24	Rint = $3 k\Omega$
t = 300ns	Cpar = 5 pF (typ)

Bottom frequency fb is set by RREF and CF:

$$f_B = \frac{l}{2 \times \{[(C_{CF} + C_{par}) \times (Xl \times R_{RREF} - R_{int})] + \tau\}} (Hz)$$

(1)

Preheat time Tpreh is set by RREF and CP:

$$T_{preh} = 674 \times \frac{C_{CP}}{100 \, nF} \times \frac{R_{RREF}}{33 \, k\Omega} (ms)$$

(2)

Ignition time Tign is set by RREF and CP:

$$T_{ign} = 611 \times \frac{C_{CP}}{100nF} \times \frac{R_{RREF}}{33k\Omega} (ms)$$
(3)

Non-overlap time Tno is set by RREF:

$$T_{no} = 0.15 + 1.25 \times \frac{R_{RREF}}{33k\Omega}(\mu s)$$

PFC on-time Ton:

$$T_{ON}(V_{VO}) = T_{ON(max)} - \frac{(T_{ON(max)} - T_{ON(min)})}{\Delta V_{VO}} \times (V_{VO} - V_{VO(low)})$$

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(4)

## **13. Test information**

The General Quality Specification for Integrated Circuits SNW-FQ-611-E is applicable.

## 14. Package outline

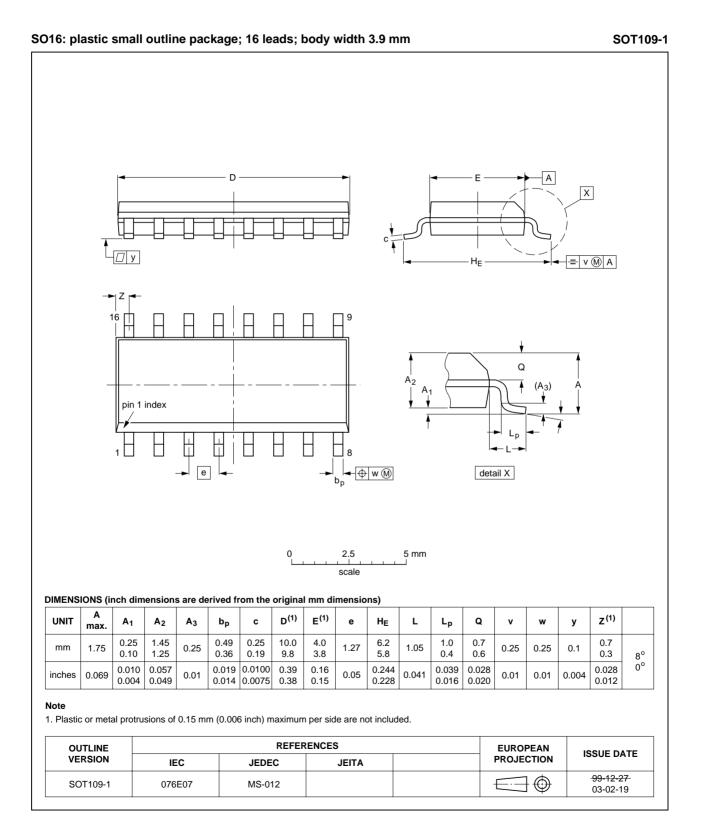
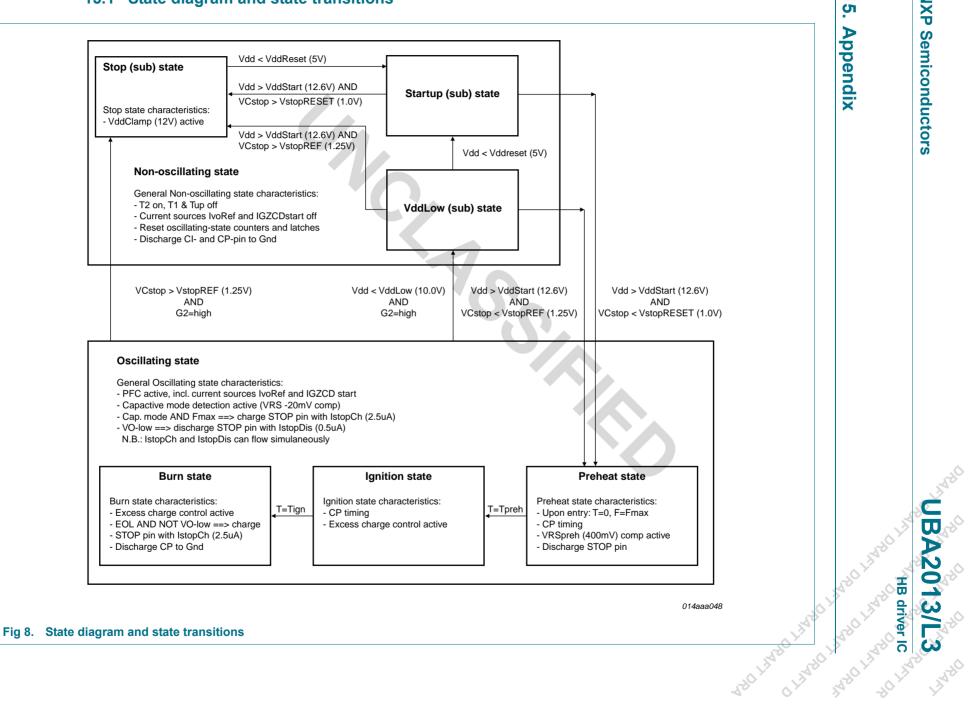


Fig 7. Package outline SOT109-1 (SO16)





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# 16. Revision history

Table 8.	<b>Revision histo</b>	ory			
Documen	t ID	Release date	Data sheet status	Change notice	Supersedes
UBA2013L	1	<yyyymmdd></yyyymmdd>	Objective data sheet	-	-

## 17. Legal information

## 17.1 Data sheet status

NXP Semiconduo	ctors	UBA2013/L3
17. Legal infor	rmation	HB driver IC
17.1 Data sheet		DRAKT DRAKT
Document status[1][2]	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.

Please consult the most recently issued document before initiating or completing a design [1]

The term 'short data sheet' is explained in section "Definitions" [2]

The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status [3] information is available on the Internet at URL http://www.nxp.com

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## 19. Tables

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## 20. Figures

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