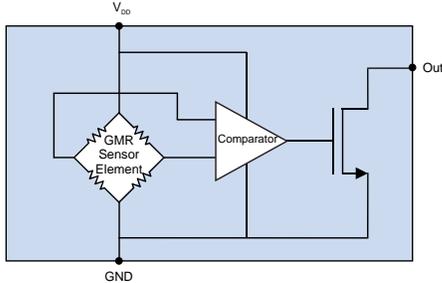


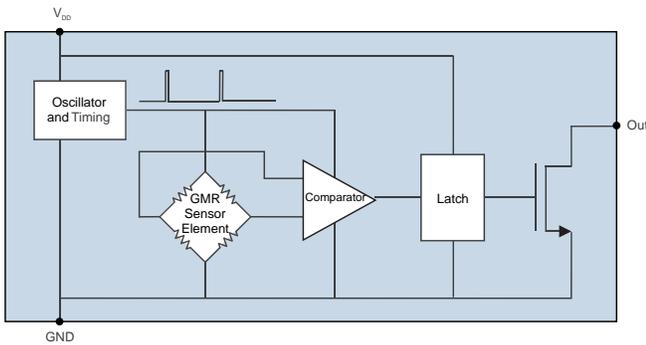
# ADLxxx Nanopower Digital Switches



## Functional Diagrams



**ADL9xx**  
(continuous duty)



**ADL0xx**  
(duty-cycled)

## Features

- 2.4 V – 3.6 V operating voltage
- Continuously operating or duty-cycled versions
- Power as low as 150 nW at 2.4 V
- Operate points as low as 20 Oe
- Precise detection of low magnetic fields
- Ultraminiature 1.1 x 1.1 mm package

## Applications

- Portable instruments
- Utility meters
- Lithium cell powered applications

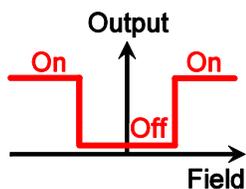
## Description

ADLxxx-Series sensors are Giant Magnetoresistive (GMR) Digital Switch devices designed to operate from 3.3-volt power supplies or single lithium cells with extremely supply low currents. The devices are manufactured with NVE’s patented spintronic GMR technology and low-power CMOS circuitry for unmatched miniaturization, sensitivity, precision, and low power.

The output is configured as a magnetic “switch” where the output turns on when the magnetic field is applied, and turns off when the field is removed. Versions are available that are either continuous duty or internally duty cycled operation to further reduce power consumption. An integrated latch ensures the output is available continuously in duty-cycled versions.

The applied field can be of either polarity, and the operate point is extremely stable over supply voltage and temperature. The output is current-sinking, and can sink up to 100 microamps.

## Idealized Magnetic Response



### Absolute Maximum Ratings

Parameter	Min.	Max.	Units
Supply voltage		5.5	Volts
Output voltage		5.5	Volts
Output current		200	μA
Storage temperature	-65	135	°C
Junction temperature		135	°C
Applied magnetic field		Unlimited	

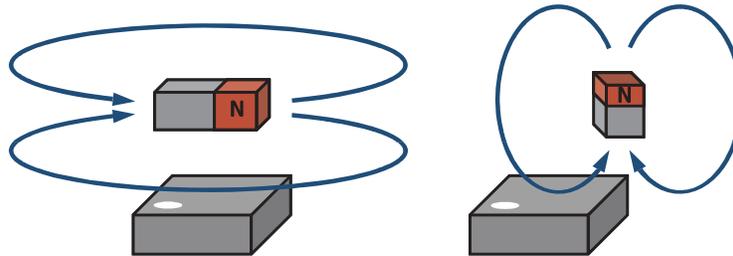
### Operating Specifications

T <sub>min</sub> to T <sub>max</sub> ; 2.4 V < V <sub>DD</sub> < 3.6 V unless otherwise stated.						
Parameter	Symbol	Min.	Typ.	Max.	Units	Test Condition
Supply voltage	V <sub>DD</sub>	2.4	3	3.6	Volts	
Operating temperature	T <sub>MIN</sub> ; T <sub>MAX</sub>	-40		125	°C	
Magnetic operate point	H <sub>OP</sub>	15	20	25	Oe	
ADLx21		21	28	34		
Operate/release differential	H <sub>OP</sub> -H <sub>REL</sub>	2		14	Oe	
Quiescent current	I <sub>DDQ</sub>		0.06	0.12	μA	V <sub>DD</sub> = 2.4V
ADL1xx			0.13	0.26		
ADL0xx			35	50		
ADL9xx			0.25	0.38		V <sub>DD</sub> = 3.6V
ADL1xx			0.35	0.65		
ADL0xx			85	120		
ADL9xx						
ADL0xx / ADL1xx peak supply current	I <sub>DD-PK</sub>		60	100	μA	V <sub>DD</sub> = 3V
Output drive current	I <sub>OL-ON</sub>	100			μA	
Output low voltage	V <sub>OL</sub>			0.2	V	V <sub>DD</sub> = 3.6V; I <sub>OL-ON</sub> = 100 μA
Output leakage current	I <sub>OL-OFF</sub>			0.005	μA	
Update frequency		10	30		Hz	
ADL1xx		20	55			
ADL0xx						
Frequency response (ADL9xx)			100		kHz	

**Operation**

**Direction of Magnetic Sensitivity**

As the field varies in intensity, the digital output will turn on and off. Unlike Hall effect or other sensors, the direction of sensitivity is in the plane of the package. The diagrams below show two permanent magnet orientations that will activate the sensor in the direction of sensitivity:



**Figure 1. Direction of magnetic sensitivity.**

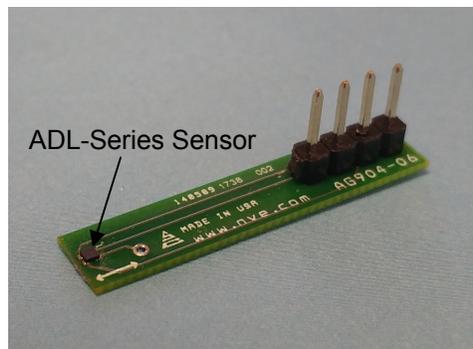
ADL-Series sensors are “omnipolar,” meaning the outputs turn ON when a magnetic field of either magnetic polarity is applied.

**External Pull-Up Resistor**

Outputs are logic low when the sensor is activated. The outputs are open-drain, and should have an external pull-up resistor. For microcontroller interfaces, the microcontroller’s input pull-up resistors can be activated.

**Typical Operation**

Figure 2 shows typical ADL-Series sensor orientation. The arrow on the circuit board shows the direction of magnetic sensitivity:



**Figure 2. Typical operation; the circuit board arrow shows direction of sensitivity.**

Typical magnetic operate and release distances for an inexpensive 4 mm diameter by 6 mm thick ceramic disk magnet, are illustrated in the following table:

Part	Operate Point (typ.)	Operate Distance (typ.)	Release Distance (typ.)
ADLx21-14E	20 Oe	10 mm	12 mm
ADLx24-14E	28 Oe	9 mm	11 mm

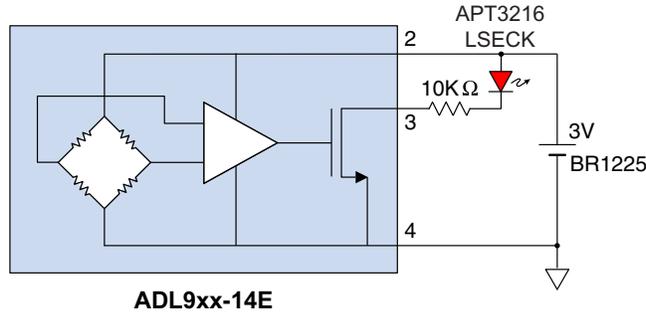
Larger and stronger magnets allow farther operate and release distances. For more calculations, use our digital sensor switching versus distance Web application at: [www.nve.com/spec/calculators.php](http://www.nve.com/spec/calculators.php).

**Illustrative Application Circuits**

**Direct-Drive LED Indicator**

Although ADLxxx-14E series sensors are not capable of driving legacy LEDs, high-efficiency LEDs such as the APT3216LSECK are visible with the 100µA drive current provided by the sensors without an external driver.

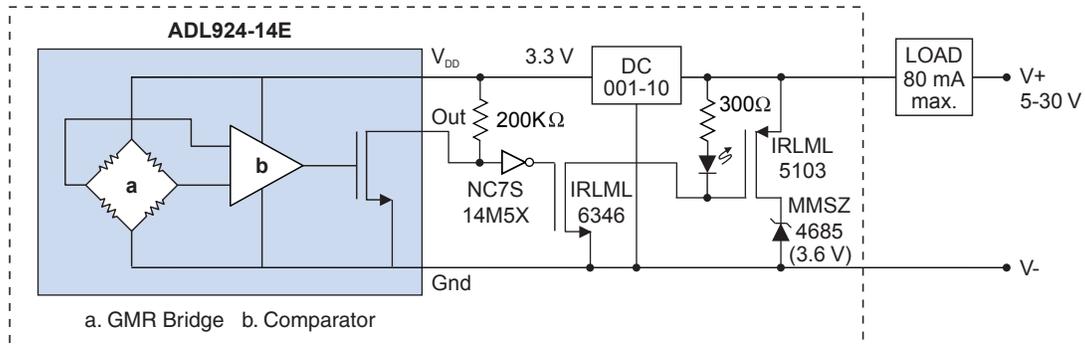
This circuit illustrates a sensor powered by a single lithium button cell with a surface-mount indicator LED:



**Figure 3. Typical ADLxxx-14E application.**

**Two-Wire Sensor Interface Using a Voltage Regulator**

ADL-Series sensors are perfect for two-wire applications, because their low supply voltage and low quiescent current provide plenty of design margin. Two-wire interfaces need to operate over a wide power supply range. With the sensor off, the circuit must draw a minimal residual current, typically less than 1.5 milliamps. With the sensor on, the circuit must provide enough current to drive a significant load such as a motor or solenoid:



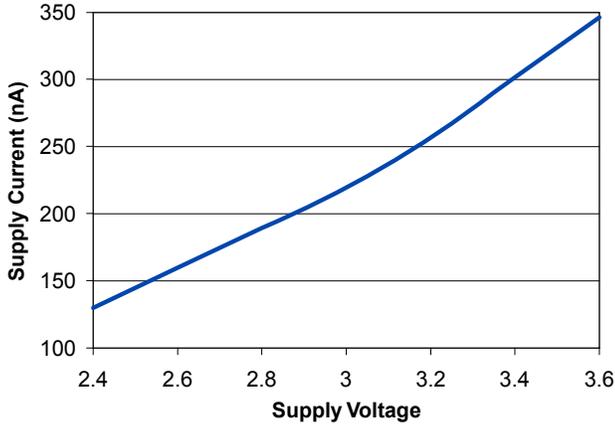
**Figure 4. Typical two-wire circuit.**

In this circuit, when a magnetic field is applied to the sensor, the MOSFETs turn on, turning on the LED and powering the load. This circuit uses an NVE DC001-10 regulator, which provides better regulation and operating latitude over the input voltage range than a Zener diode.

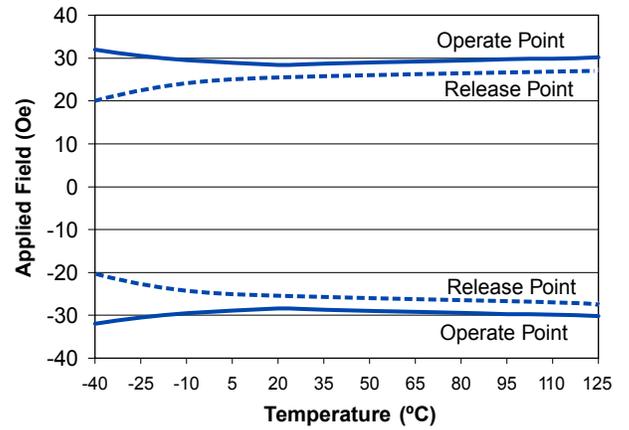
With no magnetic field and the sensor off, the residual current of the circuit is dominated by the DC001 regulator's quiescent current, which is less than one milliamp and relatively constant over input voltage. The Zener diode provides enough voltage to power the circuitry when the load is powered.

**Typical Performance**

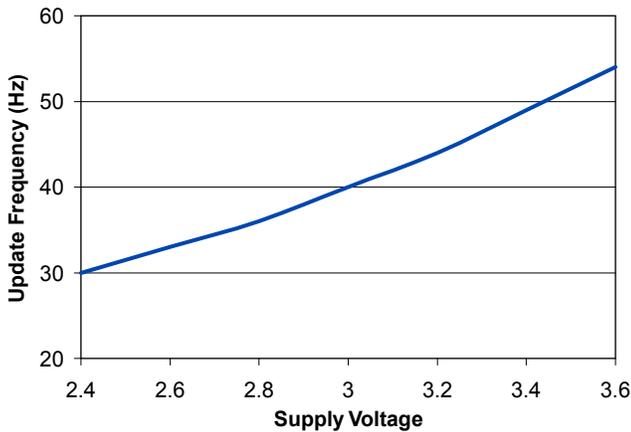
Average current increases with supply voltage but remains extremely low. The magnetic operate and release points are stable over temperature and supply voltage. Update frequency increases somewhat with supply voltage.



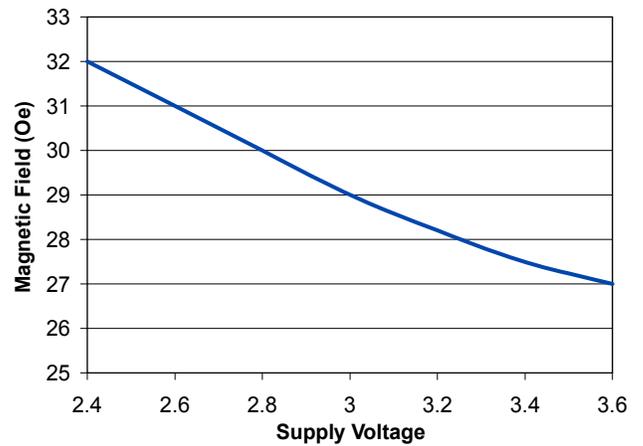
**Figure 5. Typical supply current vs. supply voltage (ADL0xx; 25°C).**



**Figure 6. Typical magnetic operate and release points vs. temperature (ADLx24; Vdd=3V).**



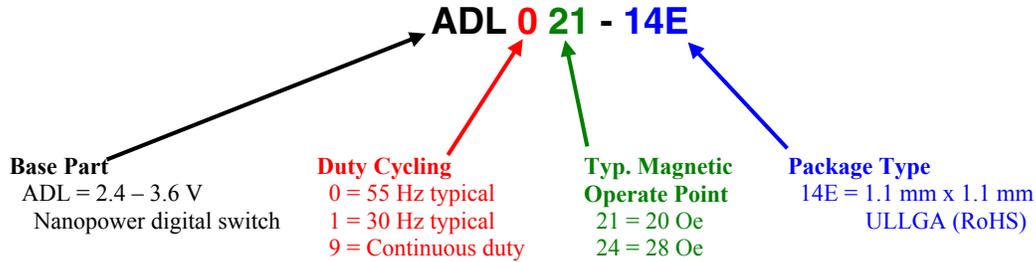
**Figure 7. Typical update frequency vs. supply voltage (ADL0xx; 25°C).**



**Figure 8. Typical magnetic operate point vs. supply voltage (ADLx24; 25°C).**

**Part Numbering**

The following example shows the ADL-Series part-numbering system:



**Available Parts**

Available Part	Duty Cycled?	Update Freq. (typ.)	Operate Point (typ.)	Package	Package Marking
ADL021-14E	Y	55 Hz	20 Oe	ULLGA	V
ADL024-14E	Y	55 Hz	28 Oe	ULLGA	C
ADL121-14E	Y	30 Hz	20 Oe	ULLGA	B
ADL124-14E	Y	30 Hz	28 Oe	ULLGA	D
ADL921-14E	N	Continuous	20 Oe	ULLGA	M
ADL924-14E	N	Continuous	28 Oe	ULLGA	N

### Evaluation Kits

NVE offers two ADL-Series Demonstration Boards, one with a battery and one without. These inexpensive evaluation kits include demo boards with the ultraminiature, ultralow-power ADL021 magnetic switch included. An LED shows the sensor output. A miniature bar magnet is included so you can see for yourself how these remarkable sensors work. These miniature evaluation boards are just 1.57 by 0.25 inches (40 x 6 mm). Images are actual size:



#### AG040C: ADL021 Externally-Powered Evaluation Board

This board has a digital output, and can be powered from a 3.3-volt nominal supply. An LED shows the output.



#### AG040B: ADL021 Battery-Powered Demonstration Board

This board is powered by a three-volt lithium coin cell (included), and the sensor quiescent power consumption is so low that the battery will last indefinitely.

### Bare Circuit Boards

NVE offers two bare circuit boards designed for easy connections to ULLGA sensors. Note that since these boards use very small sensors, they require reflow or hot-air soldering techniques. Images are actual size:



#### AG904-06: ULLGA General-Purpose PCB

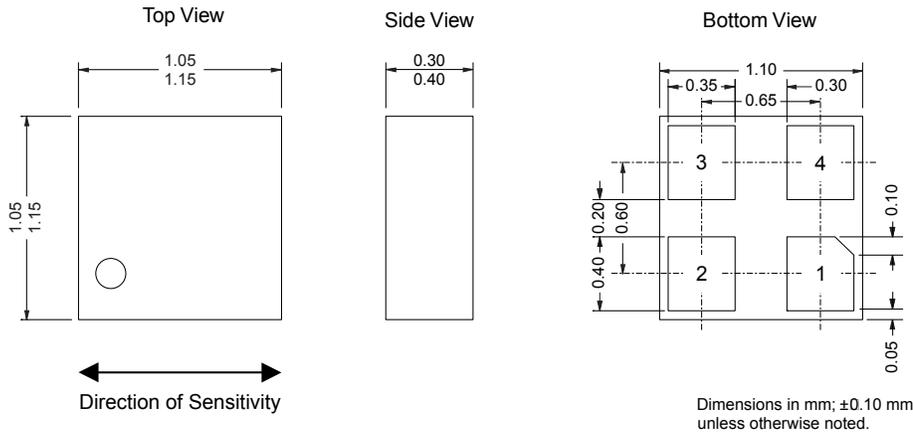
1.2 x 0.25 inch (30 x 6 mm) PCB for demonstrating 1.1 x 1.1 mm ULLGA4 sensors (-14E sensor suffix).



#### AG039-06: ULLGA Digital Sensor Demonstration Bare Board

A 1.57 x 0.25 inch PCB for demonstrating ADL-Series sensors (sensors sold separately). In addition to space for the sensor, the boards have locations for 0402-size pull-up resistors and bypass capacitors.

**1.1 mm x 1.1 mm ULLGA Package (-14E suffix)**



Pin 1	No Connect
Pin 2	V <sub>DD</sub>
Pin 3	Out
Pin 4	Ground

Soldering profile per JEDEC J-STD-020C, MSL 1.

*These products have been tested for electrostatic sensitivity to the limits stated in the specifications. However, NVE recommends that all integrated circuits be handled with appropriate care to avoid damage. Damage caused by inappropriate handling or storage could range from performance degradation to complete failure.*



**Revision History**

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**SB-00-017**

November 2017

**Change**

- Added “Typical Operation” section and image (p. 3).
- Added Evaluation Kits and bare boards (p. 7).

**SB-00-017**

October 2017

**Change**

- Revised package outline dimensions.

**SB-00-017**

May 2017

**Changes**

- Added application circuit.
- Revised quiescent current specifications.
- Added selector guide.
- Obsoleted ADLx22 versions/
- Cosmetic changes.

**SB-00-017**

December 2008

**Change**

- Initial Release.

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